

INTEGRATED THREE ECHELON INVENTORY MODEL WITH FINITE MANUFACTURING AND REMANUFACTURING RATES ALONG WITH THE TRANSPORTATION COST AND PACKAGING COST

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ABSTRACT

Supply chain means is a working togetherness of each individual's profit. In this proposed model we discuss allow the three echelon inventory model along with the transportation cost and packaging cost. Mathematical model and the numerical example are delivered for the best knowingness.

Keywords: Three Echelon, Manufacturing, Remanufacturing, Transportation cost, Packaging cost

1. INTRODUCTION

Providing satisfactory service especially that meets the demands of the customers is the most exciting part of all the administrations. Inventory control aims at minimizing inventory expenditure ensuring nonstop service throughout the supply chain of production process. Quantity of the availability of particular goods as demanded by the customer is defined as supply chain. Hence we are proving the importance of inventory in supply chain the following proposed model. Supplier, manufacturer, remanufacturer and the retailer come under the three echelon closed supply chain which is taken for analysis in this paper. The manufacturer gets the raw material from the supplier. While the newly produced products are bought from the manufacturer to the retailers. Insufficient process control, work inadequacy due to deviating instructions and improper maintenance are the result of imperfect production. Henceforth, the retailer gives the defective product to the remanufacture. The newly produced and remanufactured products fulfill the demands of the retailer in steady rate where the production rate is predictable. Similarly the steady demand of the manufacturer and remanufacturer are carried out by the supplier. One of the primary branches of the supply chain is packaging. Packaging is essential one for careful supervision, accessibility and for a deliberate. It guarantees simple treatment of things during transportation giving creation from mechanical harm expanding timeframe of realistic usability of item. Every organization are exceeding focused in quantifying their cost. This

paper extends the work of Bimal Kumar Mawandiya, J.K. Jha & Jitesh Thakkar's "Production-Inventory Model For Two-Echelon Closed Loop Supply Chain With Finite Manufacturing And Remanufacturing Rates" with the concepts of three echelon inventory model along with transportation and packaging cost. Remaining of this paper extended in the following way, Chapter 2 deals with the review of the literature, at the same time explain the notations and assumption used in the mathematical model. Chapter 3 demonstrates the mathematical model. Chapter 4 derives the numerical example for the above mathematical model, finally Chapter 5 proposes the conclusion of the proposed paper.

2. LITERATURE REVIEW

The optimization of the first inventory was introduced by Harris in the year 1913. Following him many researcher or academicians improved their inventory model with fresh philosophies. Konstantaras & Skouri 2010, Jaber & EL Saadany 2011 are discussed single echelon supply chain but multi echelon closed loop supply chain issues stated in a simple manner. Arrow et al. (1950) mainly concentrated on multi echelon inventory problem. J.F. Burns & B.D. Sivazlian, "Dynamic analysis of multi echelon supply systems" presented examined the forceful reaction of a multi echelon supply chain to several demand hired upon the organization by the end user. M.C. Van der Heijden derived a simple rule in inventory control under the evaluation short of lot sizing for multilevel supply method.

B. Pal, S. S. Sana, & K. Chaudhuri, built up a three layer combined creation stock model considering wild quality happens in supplier and remanufacture arrange. M. K. Salameh & M. Y. Jaber, stated that products are classified into two ways (i.e.) good product and defective products. And at the same time they also established if the amount of imperfect items rise then automatically the economic order quantity will rise.

Teunter (2004) made Koh et al (2002) work widespread and proposed a formula through the rate of limited production and reproduction. Jabber & EL Saadany 2011; Tgai 2012 presented a paper "An economic production and remanufacturing model with learning effects". In this paper, the processes of manufacturing and remanufacturing properties are inspected. The ideal manufacturing and reproduction policies are expressed by Chang et al (2008) to optimize the gain of the total system (consisting of supplier, manufacturer, remanufacturer and the retailer).

With the basis of the above inventory model, now we establish the paper under the concept of three echelon inventory model with following two cases.

Case-1: Each procurement lot size of raw material will be used for $n_1(k_1 = 1/n_1)$ number of production batches of the manufacturer, where n_1 is a positive integer.

Hence, the procurement lot size of raw material (Q_{f1}) in this case will be $\frac{n_1 m_1 Q_1}{f}$.

Case-2: Each production lot size of the manufacturer will use $n_2(k_2 = n_2)$ number of lots of raw material, where n_2 is a positive integer. Hence, procurement lot size of raw material (Q_{f2}) in this case will be $m_2 Q_2 / n_2 f$. The expression for the joint total cost of the system in both the cases will be different

Notations:

Develop the mathematical model the following notations and assumptions are used.

Suppliers:

- P_s : Purchasing cost of the supplier per unit
 A_s : Ordering cost of the supplier per unit
 h_s : Holding cost of the supplier per unit
 F_s : Freight cost of the supplier per unit
 PC_S : Packaging cost of the supplier per item

Manufacturer:

- P : Production rate of the manufacturer
 A_2 : Set up cost of the manufacturer per production
 A_4 : Ordering cost of the manufacturer for raw material
 h_2 : Inventory holding cost of the manufacturer for finished product per unit time
 h_4 : Inventory holding cost of the manufacturer for raw material per unit time
 f : transformation factor of finished product from the raw material
 Q_{fi} : Number of procurement of manufacturer's raw material
 T_i : Length of the production cycle in case-I (1,2)

Remanufacturer:

- P' : Production rate of the remanufacturer
 h_3^r : Inventory holding cost of the remanufacturer for raw material per unit time
 h_5 : Inventory holding cost of the remanufacturer for finished product per unit time
 r : returned part of order (which lies between 0 and 1)
 α : Transformation factor of remanufactured item from the returned item
 F_m : Shipping cost the manufacturer per delivery
 P_m : Purchasing cost of manufacturer and remanufacturer per unit
 PC_m : Packaging cost of manufacturer and remanufacturer per item

Retailer

- D : Demand of the retailer per unit time
 A_1 : Ordering cost of the retailer for the manufactured product
 A_2 : Ordering cost of the retailer for the remanufactured product
 h_1 : Holding cost of the product per unit in the retailer
 Q_i : Products supplied by the retailer from the manufacturer (decision variable) ($i=1,2$)
 m_i : Within one production cycle number of shipments made by the manufacturer to the retailer ($i=1,2$) here m_1 and m_2 are positive integer
 Q_{ri} : Product supplied by the retailer from the remanufacturer
 l_i : Within one production cycle number of shipments made by the remanufacturer to the retailer ($i=1,2$) here l_1 and l_2 are positive integer
 F_r : Transportation cost of the retailer
 P_c : selling cost of used product per unit M

- P : Substantial price perunit
- L : Employer cost perunit
- P_r : Purchasing cost of retailer perunit
- P_{Cr} : Packaging cost of the retailer per item

2.2 Assumption

1. The quality of the new product and the remanufactured product issame.
2. Constant demand is faced by theretailer.
3. Returned rate of the defective product is alsoconstant.
4. Tocomparewiththeholdingcostofthenewproductandremanufacturedproduct of the manufacturer and the remanufacturer while retailer faces highest holding cost of inventory.
5. Holding cost of raw material to produce per unit of new product is less than holding cost of newly produced product produced by themanufacturer.
6. Holding cost of returned product is less than the holding cost of the remanufactured product produced by theremanufacturer.

3. MATHEMATICAL MODEL

Here the profit of the supplier, manufacturer, remanufacturer and the retailer are depend upon the sales revenue, ordering cost of both manufactured and remanufactured product, holding cost of both manufactured and remanufactured product, transportation cost and the packaging cost.

The cost functions are defined as follows.

Supplier

Sales revenue: $P_m D$

Ordering cost: $\frac{A_s D}{n Q_1}$

Purchasing cost: $P_s D$

Holding cost: $\frac{h_s D Q_1 m_1}{2 P (1 - \alpha r)}$

Packaging cost of the raw material: $P C_s \frac{D}{Q}$

Transportation cost for the raw materials: $\frac{F_s D}{Q_1}$

Manufacturer

Sales revenue of manufacturer and remanufacturer = $P_r D$

Set up cost per production: $\frac{(1 - \alpha r) D A_2}{m_1 Q_1}$

Inventory holding cost for finished product:

$$(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} \frac{Q_1 h_2}{2}$$

Ordering cost of raw material for case (1): $\frac{(1 - \alpha r)DA_4}{n_1 m_1 Q_1}$

Ordering cost of raw material for case (2): $\frac{(1 - \alpha r)DA_4 n_2}{m_2 Q_2}$

Inventory holding cost of raw material for case (1)

$$: m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} \frac{Q_1 h_4 / f}{2}$$

Inventory holding cost of raw material for case (2): $\frac{m_2 (1 - \alpha r) Q_2 h_4 D}{2 n_2 P f}$

Packaging cost of the manufactured and remanufactured product: $PC_m \frac{D}{Q}$

Transportation cost manufactured and remanufactured product: $\frac{F_m D}{n_1 Q_1}$

Remanufacturer

Production set up cost: $(1 - \alpha r) \frac{A_3 D}{m_1 Q_1}$

Holding cost of the remanufactured product: $\frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - \left((l_1 - 2) \frac{D}{P_r} \right) \right\} \frac{Q_1 h_5}{2}$

Holding cost of the returned product: $\frac{m_1}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r} \right) \frac{Q_1 h_3}{2}$

Retailer

Sales revenue: $P_c D$

Ordering cost of new product and remanufactured product: $(1 - \alpha r) \left(A_1 + \frac{l_1 A_5}{m_1} \right) \frac{D}{Q_1}$

Holding cost of new product and remanufactured product:

$$(1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} \frac{Q_1 h_1}{2}$$

Packaging cost: $PC_r \frac{D}{Q}$

Transportation cost: $\frac{F_r D}{n_1 Q_1}$

In this paper, we concentrate on the growth of revenue of the supplier, manufacturer, remanufacturer and the retailer.

The predictable joint total profit per unit time is determined by adding the total profit of the supplier, manufacturer, remanufacturer and the retailer.

The joint total annual profit (JTP) = Supplier's total profit + manufacturer and remanufacturer's total profit + retailer's total profit

The joint total annual profit (JTP₁) =

Supplier's sales revenue – [supplier's purchasing cost + supplier's ordering cost + supplier's holding cost + supplier packaging cost + supplier transportation cost] + sales revenue of manufacturer and remanufacturer – [manufacture's inventory holding cost of finished product + manufacturer's inventory holding cost of raw material + manufacturer's ordering cost of raw material + manufacturer's production set up cost + remanufacturer

inventory holding cost of returned product + remanufacturer production set up cost +packaging cost + transportation cost] + retailer’s sales revenue – [retailer’s ordering cost of new product and remanufactured product + retailers holding cost of new product and remanufactured product + retailer’s transportation cost + retailer packaging cost +retailer transportation cost]

$$\begin{aligned}
 JTP_1 &= P_m D - \left[P_s D + \frac{A_s D}{n_1 Q_1} + \frac{h_s D Q_1 m_1}{2P(1-\alpha r)} + \frac{F_r D}{Q_1} + \frac{PC_s D}{Q_1} \right] + \\
 &P_r D - \left[(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} \frac{Q_1 h_2}{2} + m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} \frac{Q_1 h_4 / f}{2} + \right. \\
 &\frac{(1 - \alpha r) DA_4}{n_1 m_1 Q_1} + \frac{(1 - \alpha r) DA_2}{m_1 Q_1} + \frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - (l_1 - 2) \frac{D}{P'} \right\} \frac{Q_1 h_5}{2} + \frac{m_1}{\alpha} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left(1 - \right. \\
 &\left. \frac{\alpha r D}{P'} \right) \frac{Q_1 h_3}{2} + (1 - \alpha r) \frac{A_3 D}{m_1 Q_1} + \frac{F_m D}{n_1 Q_1} + \frac{PC_m D}{Q_1} \left. \right] + \\
 &P_c D - \left[(1 - \alpha r) \left(A_1 + \frac{l_1 A_5}{m_1} \right) \frac{D}{Q_1} + \left\{ (1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right)^2 \right\} \frac{m_1}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right)^2 \right\} \frac{Q_1 h_1}{2} + \frac{F_r D}{Q_1} + \frac{PC_r D}{Q_1} \right] \\
 &= P_m D - P_s D + P_r D + P_c D - \frac{F_m D}{n_1 Q_1} - \frac{A_s D}{n_1 Q_1} - \frac{PC_s D}{Q_1} - \frac{PC_m D}{Q_1} - \frac{PC_r D}{Q_1} - \frac{F_r D}{Q_1} + \frac{F_m D}{Q_1} - \frac{h_s D Q_1 m_1}{2P(1-\alpha r)} - \\
 &(1 - \alpha r) \left(A_1 + \frac{l_1 A_5}{m_1} \right) \frac{D}{Q_1} - \frac{(1 - \alpha r) DA_2}{m_1 Q_1} - (1 - \alpha r) \frac{A_3 D}{m_1 Q_1} - \frac{(1 - \alpha r) DA_4}{n_1 m_1 Q_1} - (1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right)^2 \right\} \frac{Q_1 h_1}{2} - \\
 &(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} \frac{Q_1 h_2}{2} - \frac{m_1}{\alpha} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left(1 - \frac{\alpha r D}{P'} \right) \frac{Q_1 h_3}{2} - \\
 &m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} \frac{Q_1 h_4}{2} - \frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - (l_1 - 2) \frac{D}{P'} \right\} \frac{Q_1 h_5}{2} \\
 JTP_1 &= (P_m - P_s + P_r + P_c) D - \left[\frac{A_s}{n_1} + F_r + F_s + PC_s + PC_m + PC_r + \frac{F_m}{n_1} \right] \frac{D}{Q_1} - \frac{h_s D Q_1 m_1}{2P(1-\alpha r)} - (1 - \alpha r) \left[A_1 + \right. \\
 &\left. \left[\begin{aligned} &(1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_1}{\alpha} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left(1 - \frac{\alpha r D}{P'} \right) h_3 + m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} h_4 + \\ &\frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - (l_1 - 2) \frac{D}{P'} \right\} h_5 \end{aligned} \right] \\
 &\frac{A_2}{m_1} + \frac{A_3}{m_1} + \frac{A_4}{n_1 m_1} + \frac{l_1 A_5}{m_1} \left. \right] \frac{D}{Q_1} - \frac{Q_1}{2}
 \end{aligned}$$

....(1)

Now, partially differentiate equation (1) with respect to Q_1 . We

$$\begin{aligned}
 \frac{\partial JTP_1(Q_1, m_1, n_1, l_1)}{\partial Q_1} &= \left[\frac{A_s}{n_1} + F_r + F_s + PC_s + PC_m \right] \frac{D}{Q_1^2} - \frac{h_s D m_1}{2P(1-\alpha r)} + \\
 &+ PC_r + \frac{F_m}{n_1} \\
 &(1 - \alpha r) \left[A_1 + \frac{A_2}{m_1} + \frac{A_3}{m_1} + \frac{A_4}{n_1 m_1} + \frac{l_1 A_5}{m_1} \right] \frac{D}{Q_1^2} -
 \end{aligned}$$

$$\frac{1}{2} \left[\begin{aligned} &(1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_1}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) h_3 + m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} h_4 + \\ &\frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - (l_1 - 2) \frac{D}{P_r'} \right\} h_5 \end{aligned} \right] \dots (2)$$

$$Q_1 = \frac{2PD(1 - \alpha r) \left[\begin{aligned} &\frac{A_s}{n_1} + F_r + F_s + PC_s + PC_m + PC_r + \\ &F_m + (1 - \alpha r) \left[A_1 + \frac{A_2}{m_1} + \frac{A_3}{m_1} + \frac{A_4}{n_1 m_1} + \frac{l_1 A_5}{m_1} \right] \end{aligned} \right]}{\sqrt{\left[\begin{aligned} &h_s D m_1 + P(1 - \alpha r) \\ &(1 - \alpha r) \left\{ 1 + \frac{m_1}{l_1} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_1 - 1) - (m_1 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_1}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) h_3 + m_1 \left\{ (n_1 - 1) + (1 - \alpha r) \frac{D}{P} \right\} h_4 + \\ &\frac{m_1 \alpha r}{l_1} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_1 - 1) - (l_1 - 2) \frac{D}{P_r'} \right\} h_5 \end{aligned} \right]} \dots (3)$$

Equation (3) proposes the corresponding optimal order quantity of case (1) per unit time.

The predictable joint total profit per unit time for case -2 written as follows

$$\begin{aligned} JTP_2 &= P_m D - \left[P_s D + \frac{A_s D}{n_2 Q_2} + \frac{F_s D}{Q_2} + \frac{h_s D Q_2 m_2}{2P(1 - \alpha r)} + \frac{PC_s D}{Q_2} \right] + \\ &P_r D - \left[(1 - \alpha r) \left\{ (m_2 - 1) - (m_2 - 2) \frac{D}{P} \right\} \frac{Q_2 h_2}{2} + \frac{m_2}{n_2} \left\{ (1 - \alpha r) \frac{D}{P} \right\} \frac{Q_2 h_4 / f}{2} + \frac{(1 - \alpha r) n_2 D A_4}{m_2 Q_2} + \right. \\ &\frac{(1 - \alpha r) D A_2}{m_2 Q_2} + \frac{m_2 \alpha r}{l_2} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_2 - 1) - (l_2 - 2) \frac{D}{P_r'} \right\} \frac{Q_2 h_5}{2} + \frac{m_2}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) \frac{Q_2 h_3}{2} + \\ &\left. (1 - \alpha r) \frac{A_3 D}{m_2 Q_2} + \frac{F_m D}{n_2 Q_2} + \frac{PC_m D}{Q_2} \right] + \\ &P_c D - \left[(1 - \alpha r) \left(A_1 + \frac{l_2 A_5}{m_2} \right) \frac{D}{Q_2} + (1 - \alpha r) \left\{ 1 + \frac{m_2}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} \frac{Q_2 h_1}{2} + \frac{PC_r D}{Q_2} + \frac{F_r D}{Q_2} \right] \\ &= P_m D - P_s D + P_r D + P_c D - \frac{A_s D}{n_2 Q_2} - \frac{F_r D}{Q_2} - \frac{F_s D}{Q_2} - \frac{F_m D}{n_2 Q_2} - \frac{h_s D Q_2 m_2}{2P(1 - \alpha r)} - \frac{PC_s D}{Q_2} - \frac{PC_m D}{Q_2} - \frac{PC_r D}{Q_2} - \\ &(1 - \alpha r) \left(A_1 + \frac{l_2 A_5}{m_2} \right) \frac{D}{Q_2} - \frac{(1 - \alpha r) D A_2}{m_2 Q_2} - (1 - \alpha r) \frac{A_3 D}{m_2 Q_2} - \frac{(1 - \alpha r) D n_2 A_4}{m_2 Q_2} - \\ &(1 - \alpha r) \left\{ 1 + \frac{m_2}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} \frac{Q_2 h_1}{2} - (1 - \alpha r) \left\{ (m_2 - 1) - (m_2 - 2) \frac{D}{P} \right\} \frac{Q_2 h_2}{2} - \frac{m_2}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \right. \\ &\left. \frac{\alpha r D}{P_r'} \right) \frac{Q_2 h_3}{2} - \frac{m_2}{n_2} \left\{ (1 - \alpha r) \frac{D}{P} \right\} \frac{h_4 Q_2}{2f} - \frac{m_2 \alpha r}{l_2} \left(\frac{\alpha r}{(1 - \alpha r)} \right) \left\{ (l_2 - 1) - (l_2 - 2) \frac{D}{P_r'} \right\} \frac{Q_2 h_5}{2} \\ JTP_2 &= (P_m - P_s + P_r + P_c) D - \left[\frac{A_s}{n_2} + F_r + F_s + PC_s + PC_m + PC_r + \frac{F_m}{n_2} \right] \frac{D}{Q_2} - \frac{h_s D Q_2 m_2}{2P(1 - \alpha r)} - \\ &(1 - \alpha r) \left[A_1 + \frac{A_2}{m_2} + \frac{A_3}{m_2} + \frac{n_2 A_4}{m_2} + \frac{l_2 A_5}{m_2} \right] \frac{D}{Q_2} \end{aligned}$$

$$-\frac{Q_2}{2} \left[\begin{aligned} &(1 - \alpha r) \left\{ 1 + \frac{m_2}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_2 - 1) - (m_2 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_2}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) h_3 + \frac{m_2}{n_2} \left\{ (1 - \alpha r) \frac{D}{P} \right\} \frac{h_4}{f} \\ &+ \frac{m_2 \alpha r}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right) \left\{ (l_2 - 1) - (l_2 - 2) \frac{D}{P_r'} \right\} h_5 \end{aligned} \right] \dots (4)$$

Now partially differentiate equation (5) with respect to Q_2 . We get,

$$\begin{aligned} \frac{\partial JTP_2(Q_2, m_2, n_2, l_2)}{\partial Q_2} &= \left[\frac{A_s}{n_2} + F_r + PC_s + F_s + \right] \frac{D}{Q_2^2} - \frac{h_s D m_2}{2P(1 - \alpha r)} \\ &+ (1 - \alpha r) \left[A_1 + \frac{A_2}{m_2} + \frac{A_3}{m_2} + \frac{n_2 A_4}{m_2} + \frac{l_2 A_5}{m_2} \right] \frac{D}{Q_2^2} \\ &- \frac{1}{2} \left[\begin{aligned} &(1 - \alpha r) \left\{ 1 + \frac{m_2}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_2 - 1) - (m_2 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_2}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) h_3 + \frac{m_2}{n_2} \left\{ (1 - \alpha r) \frac{D}{P} \right\} \frac{h_4}{f} + \\ &\frac{m_2 \alpha r}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right) \left\{ (l_2 - 1) - (l_2 - 2) \frac{D}{P_r'} \right\} h_5 \end{aligned} \right] \dots (5) \end{aligned}$$

$$Q_2 = \sqrt{\frac{2PD(1 - \alpha r) \left[\frac{A_s}{n_2} + F_r + PC_r + PC_s + PC_m + F_s + \frac{F_m}{n_2} + (1 - \alpha r) \left[A_1 + \frac{A_2}{m_2} + \frac{A_3}{m_2} + \frac{n_2 A_4}{m_2} + \frac{l_2 A_5}{m_2} \right] \right]}{h_s D m_2 + P(1 - \alpha r) \left[\begin{aligned} &(1 - \alpha r) \left\{ 1 + \frac{m_2}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right)^2 \right\} h_1 + \\ &(1 - \alpha r) \left\{ (m_2 - 1) - (m_2 - 2) \frac{D}{P} \right\} h_2 + \\ &\frac{m_2}{\alpha} \left(\frac{\alpha r}{1 - \alpha r} \right) \left(1 - \frac{\alpha r D}{P_r'} \right) h_3 + \\ &\frac{m_2}{n_2} \left\{ (1 - \alpha r) \frac{D}{P} \right\} \frac{h_4}{f} + \\ &+ \frac{m_2 \alpha r}{l_2} \left(\frac{\alpha r}{1 - \alpha r} \right) \left\{ (l_2 - 1) - (l_2 - 2) \frac{D}{P_r'} \right\} h_5 \end{aligned} \right]} \dots (6)$$

Equation (6) proposes the corresponding optimal order quantity per unit time for case (2)

4. NUMERICAL EXAMPLE

$D = 1000, P = 9400, P_s = 20, A_s = 50, h_s = 2, F_s = 50, A_1 = 100, A_2 = 400, A_3 = 200, A_4 = 250, A_5 = 75, F_m = 50, P_m = 35, h_1 = 40, h_2 = 20, h_3 = 8, h_4 = 12, h_5 = 15, P_r' = 12000, P_r = 50, F_r = 65, P_c = 70, m_1 = 12.43, l_1 = 3.726, n_1 = 1, m_2 = 15.13, l_2 = 4.53, n_2 = 4.83, \alpha = 0.9, f = 0.8, r = 0.25, PC_r = 25, PC_m = 15, PC_s = 8$

SOLUTION:

Equation (3) and (6) gives the optimal order quantity. Now, substitute the above values in this equations we get $Q_1=57$, $Q_2= 50$ for case 1 and case 2 respectively.

The joint total profit with respect to case 1 and case 2 are **1, 20,570** and **1, 21,224** respectively.

5. CONCLUSION:

Here the mathematical model has been developed for the maximization of the total profit of the three echelon closed loop supply chain consisting of the supplier, manufacturer, remanufacturer and the retailer when the demand is considered as constant, at the same time returned rate from the retailer is also considered as constant. The numerical example provides the better consideration to the suggested

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